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Distributed parameter models accurately predict vibration and noise in many manufacturing, space, HVAC, robotics, transportation, and power transmission systems. This book presents recent advances in the application of Lyapunov's method to the control of distributed vibration and noise. The book focuses on the development of adaptive, output feedback controllers that provide asymptotic
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Vibration and noise reduce the perceived quality, productivity, and efficiency of many and limit production speeds electromechanical systems.

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Mechatronic Control of Distributed Noise and Vibration

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